## hamatic compact data sheet



## Technical data

|  | S 95/ SH 95 | S 80/ SH 80 S 56/ SH 56 |
| :---: | :---: | :---: |
| Mains voltage | $\begin{aligned} & \text { 1~ } 100 / 115 / 230 \mathrm{~V} \mathrm{AC} \pm 10 \% 50 / 60 \mathrm{~Hz} \\ & 3 \sim 400 / 480 \mathrm{~V} \pm 10 \% 50 / 60 \mathrm{~Hz} \\ & 36 \mathrm{~V} \text { DC via hatronic compact } \\ & \text { frequency inverter DC-FI } \end{aligned}$ | 1~ $100 / 115 / 230$ V AC $\pm 10 \% 50 / 60 \mathrm{~Hz}$ 36 V DC via hatronic compact frequency inverter DC-FI |
| Spindle lenght S | According to customer requirements |  |
| Stroke SH | $100,200,250,300$ and 500 mm , others on request |  |
| Duty cycle | 25 s on / 400 s off |  |
| Control options | Direct control via rated voltage <br> - Via hatronic control CTRL <br> Via hatronic compact frequency inverter DC-FI |  |
| End position limitation | On request for SH-versions |  |
| Position detection | Hall sensor on request |  |



Force-speed diagram 100/115/230 V 1~60 Hz


- S/SH 56

■ S/SH 80 S/SH 95

Force-speed diagram S / SH 95 400/480 V 3~50 Hz


- 50 Hz

Force-speed diagram S / SH 95 400/480 V 3~ 60 Hz


- 60 Hz


S 95 with continuous spindle



## Option: Travel tube S 95



Option: Fork joint S 95 / SH 95



S 80 with continuous spindle




Option: Fork joint S 80 / SH 80



S 56 with continuous spindle


A, B, C, D = Cable outlet



Option: Spindle nut S 56


## Option: Fork joint S 56 / SH 56



SH 56


